

Performance Evaluation of Bit Flipping and Sum Product Algorithm of LDPC coder in different channel environment

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Abstract— Low Density Parity Check (LDPC) codes are one of the block coding techniques that can approach the Shannon's limit within a fraction of a decibel for high block lengths. In many digital communication systems, these codes have strong competitors of turbo codes for error control. LDPC codes performance depends on the excellent design of parity check matrix and many diverse research methods have been used by different study groups to evaluate the performance. Unlike many other classes of codes, LDPC codes are already equipped with a fast, probabilistic decoding algorithm. This makes LDPC codes not only attractive from a theoretical point of view, but also very suitable for practical applications. This paper throws hard decision and soft decision algorithm of LDPC. The hard decision algorithm contains Bit flipping algorithm and Soft decoding algorithm contains Sum product algorithm which is used to correct burst error. Sum Product algorithm is also called as belief propagation. Bit flipping and Sum Product algorithms are explained and can be implemented for the generated parity check matrix of (648,324) for LDPC code with code rate 1/2.

Keywords- Encoder, Bit Flipping Algorithm, Sum Product Algorithm, AWGN, Rayleigh and Rician Channel

I. INTRODUCTION

Low-density parity-check (LDPC) codes are a class of linear block codes with implementable decoders, which provide near-capacity performance on a large set of data transmission and data-storage channels. Low-density parity-check (LDPC) codes were first introduced by R.G.Gallager[1] and rediscovered by MacKay in 1996[2]. Davey and Mackay rediscovered that by extending the order of Galois Field GF (q)[3]. This class of codes is known as non-binary LDPC codes. These codes are showing more and more competitive and have become some error-correcting code standards or the candidate standard in communication system.

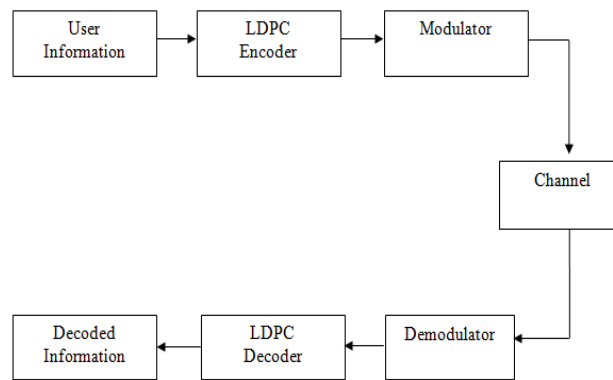
LDPC codes were invented by Gallager in his 1960 doctoral dissertation and were mostly ignored during the 35 years that followed[2]. One notable exception is the important work of Tanner in 1981, in which Tanner generalized LDPC codes and introduced a graphical representation of LDPC codes, now called a Tanner graph[4]. The study of LDPC codes was resurrected in the mid 1990s with the work of MacKay, Luby, who noticed, apparently independently of Gallager's work, the advantages of linear block codes with sparse (low-density) parity-check matrices[5].

The Bit-Flipping (BF) decoding algorithm[6], which was proposed by Gallager in 1962, and rediscovered by Mackay and Neal in 1996, is based on the hard decision of symbol. BF is simple and easy to be implemented, but has only limited decoding performance. Well designed LDPC codes decoded with iterative decoding based on belief propagation algorithm, such as the sum product algorithm (SPA)[7] achieve performance close to the Shannon limit 0.0045[8].

The paper is organized as follows: Section I the introduction of LDPC is explained. Section II is containing block diagram of the coded system. Section III is containing encoding method of LDPC for generating codeword that is transmitted on channel. Section IV decoding methods of LDPC in this section Bit Flipping (Hard Decision) and Sum Product (soft Decision) algorithm of the decoder is explained. Section V Results and analysis for different decoding algorithm explained. Section VI contains Conclusion.

II. BLOCK DIAGRAM OF CODED SYSTEM

The basic model of coded system, which is given in Figure 1-2, consists of five elements; encoder, modulator, channel, demodulator and decoder are shown in Fig. 1. The encoder for a LDPC divides the information sequence into message blocks of k information bits each. A message block is represented by the binary k-tuple $u=(u_0, u_1, \dots, u_{k-1})$ called a message. There are a total of 2^k different possible messages. The encoder transforms each message u independently into an n-tuple $v=(v_0, v_1, \dots, v_{n-1})$ of discrete symbols called a codeword.

Fig. I Coded System^[2]

As shown in Fig. 1 encoder may encode user information by using encoding process of low density parity check (LDPC) code. The result of encoding user information is codeword denoted as w . Codeword may be of a predetermined length, which may be referred to as n , where $n \geq k$. Codeword may include non-binary symbols corresponding to any of the elements in Galois Field (q), where q denotes the number of elements in the Galois Field. Codeword may be referred to as a GF(q) codeword.

Codeword is passed to a modulator. Modulator prepares codeword for transmission on channel. Modulator may use phase shift keying, frequency-shift keying, quadrature amplitude modulation, or any suitable modulation technique to modulate codeword into one or more information-carrying signals [2]. Channel may represent media through which the Information-carrying signals travel. For example, channel may represent a Wired or Wireless medium in a communication system.

Due to interference signals and other types of noise and phenomena, channel may corrupt the waveform transmitted by modulator. Thus, the waveform received by demodulator [1]. Received waveform may be different from the originally transmitted signal waveform. Received waveform may be demodulated with demodulator. The result of demodulation is received vector, which may contain errors due to channel corruption. Each entry in received vector may be referred to as a symbol or a variable. Each variable or symbol may be one of multiple non-binary values. Received vector may then be processed (decoded) by LDPC decoder. This processing may also equivalently be referred to as decoding a non-binary LDPC code or a received vector. LDPC decoder may be a non-binary code decoder. LDPC decoder may be used to correct or detect errors in received vector.

III. ENCODING

There are plenty of methods used for generating parity check matrix and Generator matrix. Parity check matrix is generated using Base matrix which consists of many sub matrices within it. Memory requirement is quite crucial issue during the VLSI implementation of LDPC codes. Generation of Parity check matrix using Base matrix requires less memory. Parity check matrix is obtained after expansion of Base matrix. Base matrix has elements like 0, -1 and any number between 0 to $Z-1$, where Z is an expansion factor. During expansion, -1 is replaced by $Z \times Z$ all zero matrix and any number between 0 to $Z-1$ is replaced by $Z \times Z$ identity matrix circular shifted by that number that shown in Fig. 2. Many of the standards like 802.11n, 802.16e etc. uses this method. Parity check matrix of size 324×648 is used for the simulation. Generator matrix is generated from parity check matrix using Gauss elimination method [5].

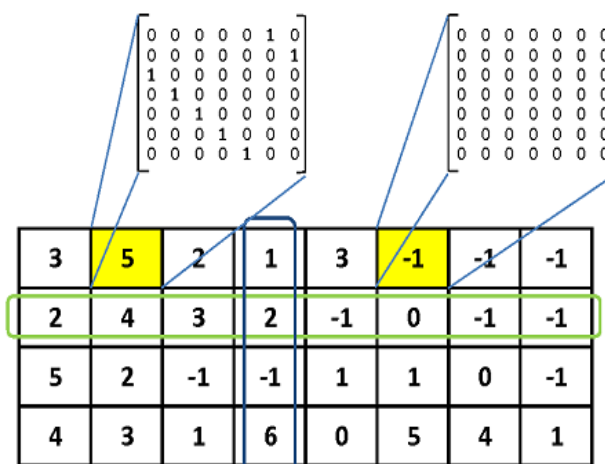


Fig. 2 Base matrix having expansion factor 7

A. Gauss Elimination Method

The conventional method of encoding with the generator matrix is derived from parity check matrix by (modulo-2) Gauss elimination. This method is used for finding the unknown generator matrix G from the Parity Check Matrix (PCM) achieved through row permutations, modulo-2 sums of rows and also some column permutation [5]. The generator matrix G is given by $G = \{A^T | I_k\}$. It is used to reduce H into row-echelon form by applying elementary row operations. The encoded codeword c is

derived from the matrix multiplication $c = u \times G$, where u is the message to be transmitted. The encoding process consists of normal matrix multiplication.

IV. DECODING ALGORITHM OF LDPC CODER

The algorithm used to decode LDPC codes was discovered independently several times and as a matter of fact comes under different names. The most common ones are the belief propagation algorithm, the message passing algorithm and the sum-product algorithm [7]. In order to explain this algorithm, a very simple variant which works with hard decision [6], will be introduced first. Later on the algorithm will be extended to work with soft decision which generally leads to better decoding results.

Tanner designed LDPC codes with a graphical representation method which called Tanner graph [4]. Tanner graph can express the decoding process of LDPC codes effectively and completely. For an example of Tanner graph with (8, 4) LDPC code is given in Figure 2 and it can describe a regular parity check matrix H intuitively in Eq. 1. Tanner graph has two different nodes which are the variable nodes (v-node) and the check nodes (c-node). Each row of a parity check matrix H is to match each check node of Tanner graph, and each column of a parity check matrix H is to match each variable node of Tanner graph. Check node i is connected to neighbor variable node j when h_{ij} in H is assigned to 1. Otherwise, it is not connected the value of this element is 0. Therefore, n variable nodes and $m = n - k$ check nodes are existed in a parity check matrix H and are matched to Tanner graph.

$$H = \begin{bmatrix} 0 & 1 & 0 & 1 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 & 1 & 0 & 1 & 0 \end{bmatrix} \quad (1)$$

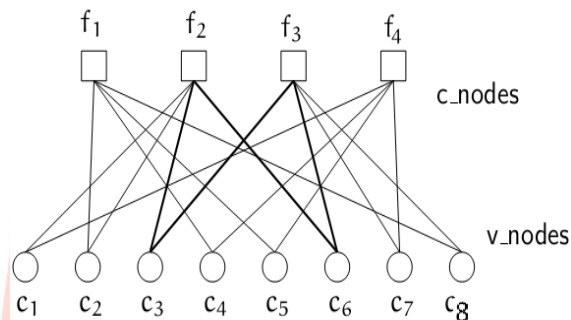


Fig. 3 Graphical representation of tanner graph for LDPC code

A. Hard Decision (Bit Flipping) Algorithm

Here Hard Decision (Bit Flipping) Algorithm is explain by one example. An error free codeword of H is $c = [1 \ 0 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1]$. Suppose we receive $y = [1 \ 1 \ 0 \ 1 \ 0 \ 1 \ 0 \ 1]$. So c_2 was flipped. The algorithm is as follow

Step 1. All v-nodes c_i send a "message" to their c-nodes f_j containing the bit they believe to be the correct one for them. At this stage the only information a v-node c_i is the corresponding received i^{th} bit of c . That means for example, that c_1 sends a message containing 1 to f_1 and f_3 , node c_2 sends messages containing y_1 (1) to f_1 and f_2 , and so on.

Step 2. Every check nodes calculate a response to their connected message nodes using the messages they receive from step 1. The response message in this case is the value (0 or 1) that the check node believes the message node has based on the information of other message nodes connected to that check node. This response is calculated using the parity-check equations which force all message nodes connect to a particular check node to sum to 0 (mod 2).

Table 1. Check nodes activities for hard-decision Decoder for code of Fig. 3

check nodes	activities				
f_1	receive	$c_2 \rightarrow 1$	$c_4 \rightarrow 1$	$c_5 \rightarrow 0$	$c_8 \rightarrow 1$
	send	$0 \rightarrow c_2$	$0 \rightarrow c_4$	$1 \rightarrow c_5$	$0 \rightarrow c_8$
f_2	receive	$c_1 \rightarrow 1$	$c_2 \rightarrow 1$	$c_3 \rightarrow 0$	$c_6 \rightarrow 1$
	send	$0 \rightarrow c_1$	$0 \rightarrow c_2$	$1 \rightarrow c_3$	$0 \rightarrow c_6$
f_3	receive	$c_3 \rightarrow 0$	$c_6 \rightarrow 1$	$c_7 \rightarrow 0$	$c_8 \rightarrow 1$
	send	$0 \rightarrow c_3$	$1 \rightarrow c_6$	$0 \rightarrow c_7$	$1 \rightarrow c_8$
f_4	receive	$c_1 \rightarrow 1$	$c_4 \rightarrow 1$	$c_5 \rightarrow 0$	$c_7 \rightarrow 0$
	send	$1 \rightarrow c_1$	$1 \rightarrow c_4$	$0 \rightarrow c_5$	$0 \rightarrow c_7$

In Table 1, check node f_1 receives 1 from c_4 , 0 from c_5 , 1 from c_8 thus it believes c_2 has 0 ($1+0+1+0=0$), and sends that information back to c_2 . Similarly, it receives 1 from c_2 , 1 from c_4 , 1 from c_8 thus it believes c_5 has 1 ($1+1+1+1=0$), and sends 1

back to c_5 . At this point, if all the equations at all check nodes are satisfied, meaning the values that the check nodes calculate match the values that receive, the algorithm terminates. If not, we move on to step 3.

Step 3. In this step, the message nodes use the messages they get from the check nodes to decide if the bit at their position is a 0 or a 1 by majority rule. The message nodes then send this hard-decision to their connected check nodes. Table 2 illustrates this step. To make it clear, let us look at message node c_2 . It receives 2 0's from check nodes f_1 and f_2 . Together with what it already has $y_2 = 1$, it decides that its real value is 0. It then sends this information back to check nodes f_1 and f_2 .

Table 2. Message nodes decisions for hard decision Decoder for code of Fig. 3

message nodes	y_i	messages from check nodes		decision
c_1	1	$f_2 \rightarrow 0$	$f_4 \rightarrow 1$	1
c_2	1	$f_1 \rightarrow 0$	$f_2 \rightarrow 0$	0
c_3	0	$f_2 \rightarrow 1$	$f_3 \rightarrow 0$	0
c_4	1	$f_1 \rightarrow 0$	$f_4 \rightarrow 1$	1
c_5	0	$f_1 \rightarrow 1$	$f_4 \rightarrow 0$	0
c_6	1	$f_2 \rightarrow 0$	$f_3 \rightarrow 1$	1
c_7	0	$f_3 \rightarrow 0$	$f_4 \rightarrow 0$	0
c_8	1	$f_1 \rightarrow 1$	$f_3 \rightarrow 1$	1

Step 4. Repeat step 2 until either exit at step 2 or a certain number of iterations has been passed. In this example, the algorithm terminates right after the first iteration as all parity check equations have been satisfied. c_2 is corrected to 0.

B. Soft-Decision Algorithm

The above description of hard-decision decoding was mainly for educational purpose to get an overview about the idea. Soft-decision decoding of LDPC codes [7], which is based on the concept of belief propagation, yields in a better decoding performance and is therefore belief propagation the preferred method.

The soft-decision decoder operates with the same principle as the hard-decision decoder, except that the messages are the conditional probability that the received bit is a 1 or a 0 given the received vector y .

let $P_i = \Pr(c_i = 1|y_i)$ be the conditional probability that c_i is a 1 given the value of y and let $\Pr(c_i = 1|y_i) = 1 - P_i$. q_{ij} is a message sent by the variable node c_i to the check node f_j . Every message contains always the pair $q_{ij}(0)$ and $q_{ij}(1)$ which stands for the amount of belief that y_i is a "0" or a "1".

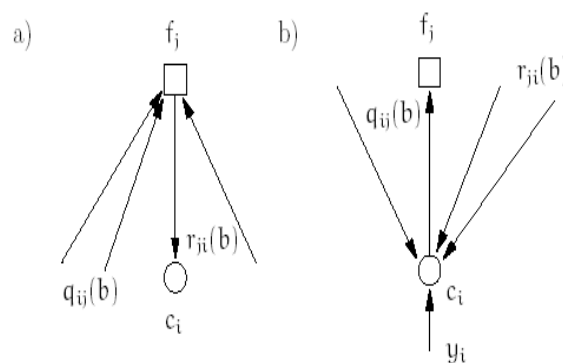


Fig. 3 VN Decoder and CN decoder

r_{ji} is a message sent by the check node f_j to the variable node c_i . Again there is a $r_{ji}(0)$ and $r_{ji}(1)$ that indicates the (current) amount of belief in that y_i is a "0" or a "1". The step numbers in the following description correspond to the hard decision case.

Step 1. All variable nodes send their q_{ij} messages to check node from below equation

$$q_{ij}(1) = P_i \text{ and } q_{ij}(0) = 1 - P_i \quad (2)$$

Step 2. The check nodes calculate their response messages r_{ji}

$$r_{ji}(0) = \frac{1}{2} + \frac{1}{2} \prod_{i' \in v_j \setminus i} (1 - 2q_{i'j}(1)) \quad (3)$$

$$r_{ji}(1) = 1 - r_{ji}(0) \quad (4)$$

So they calculate the probability that there is an even number of 1's among the variable nodes except c_i (this is exactly what V_{ji} means). This probability is equal to the probability $r_{ji}(0)$ that c_i is a 0. This step and the information used to calculate the responses is illustrated in Fig. 3.

Step 3. The variable nodes update their response messages to the check node c_i to the variable node f_j . This is done according to the following equations,

$$q_{ij}(0) = k_{ij}(1 - P_i) \prod_{j' \in C_i / j} r_{j'i}(0) \quad (5)$$

$$q_{ij}(1) = k_{ij}P_i \prod_{j' \in C_i / j} r_{j'i}(1) \quad (6)$$

Where by the Constants K_{ij} are chosen in a way to ensure that $q_{ij}(0) + q_{ij}(1) = 1$. C_{ij} now means all check nodes except f_j . At this point the v-nodes also update their current estimation their variable c_i . This is done by calculating the probabilities for 0 and 1 and voting for the bigger one. The used equations are quite similar to the ones to compute $q_{ij(b)}$ but now the information from every c-node is used.

$$Q_i(0) = K_i(1 - P_i) \prod_{j \in C_i} r_{ji}(0) \quad (7)$$

$$Q_i(1) = K_iP_i \prod_{j \in C_i} r_{ji}(1) \quad (8)$$

If the current estimated codeword fulfills now the parity check equations the algorithm terminates. Otherwise termination is ensured through a maximum number of iterations.

$$C_i = \begin{cases} 1 & \text{if } Q_i(1) > Q_i(0) \\ 0 & \text{else} \end{cases} \quad (9)$$

V. RESULTS AND ANALYSIS

In this section, the BER performance for the Hard decision (Bit flipping) and Soft decision (Sum Product) algorithms with irregular (324,648) LDPC codes with codeword length is 648 and code rate is 0.5 are implemented. The simulations are performed over an additive white Gaussian noise (AWGN), Rayleigh and Rician channel with BPSK modulation.

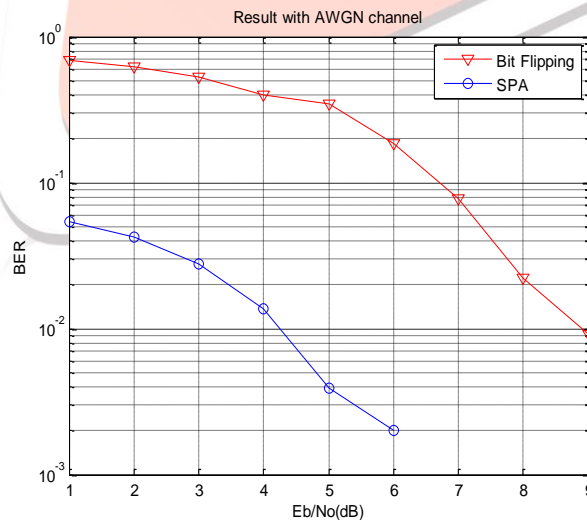


Fig. 4 Simulation result for BF and SPA algorithm for AWGN channel

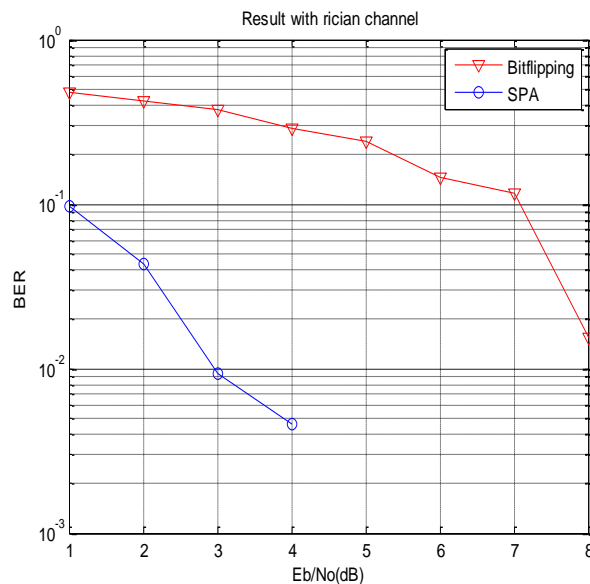


Fig. 5 Simulation result for BF and SPA algorithm for Rician channel

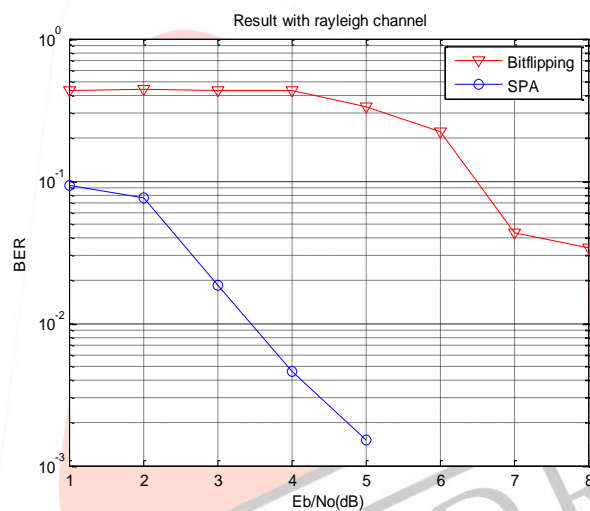


Fig. 6 Simulation result for BF and SPA algorithm for Rayleigh channel

Fig. 4, Fig. 5 and Fig. 6 are shows BER Vs SNR is plotted for the Hard decision (Bit flipping) and Soft decision (Sum Product) algorithms for the different channel environment. BER performance of the soft decision (SPA) algorithm is improves by compare hard decision (BFA). For Rician channel BER performance of both algorithm is improve by comparing with AWGN and Rayleigh channel.

VI. CONCLUSIONS

BER Performance for Sum Product Algorithm and Bit Flipping Algorithm is checked with different channel environment. It is observed that for Rician channel BER performance of both algorithm is improve as comparing with AWGN and Rayleigh channel. It can be seen from BER performance that the Sum Product Algorithm is better in comparison with Bit flipping Algorithm.

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