Low Power Laser Based Breath Detecting System

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Abstract — In this paper, A low-power Laser projector and a Webcam are used to design a monitor system for the body breath detection, which monitors and records the patient’s breath and sends the information to the server. Our system consists of two parts in which the first part has a Webcam, which is used to capture the images of the reflection from a low-power laser projector and transmits it to a PC. For the second part, an image processing program using the temporal differencing algorithm is used to detect the reflective mark movement to determine the breath rate, installed in the PC. The low-power laser which we are using in this project is safe for the patients.


I. INTRODUCTION

The traditional ways of monitoring the breath rate involve contact with the human body. For example, for Impedance Pneumography, one side of the electrode, which is placed on the skin of the chest, sends a high-frequency current and concurrently uses the other side of the receiving electrode to receive the current changes that take place during a breathing cycle. The earlier methods require some sort of tying up or other contact with the body. Thus there is a need to design a method of breath detection that avoids contact with the human body.

Our design detects chest expansion and contraction in a way that is similar to the detection of a moving object by laser reflection. There are three major methods used to detect a moving object. First, “temporal differencing” is used to find the difference between two continuous image data and obtains the changes in the volume of a moving object. If the background variation is not great, this method works well. Second, “background subtraction” establishes the background of the images and then inputs one image after another in order to cancel the background and to obtain the moving object. This method, which produces a complete outline of moving objects, is very sensitive to changes in the environment because the background is established from the very beginning. Third, “optical flow” calculates moving locations in time to discern each pixel in the image.

After comparing these three methods we have used the image processing method with “temporal differencing” in our design. This method has a higher image processing speed and its use in the circuit board will not cause much of the complexity in the circuit. To enhance the accuracy of our detection system we measure the breath twice instead of a single laser reflection. This design provides more amplification of the chest contraction from the breath and reduces the system detection error.

II. OPERATION OF THE SYSTEM

Fig 1 indicates block diagram. First we use a low power laser irradiating a patient’s chest with a smooth reflection surface and let the laser reflect this onto a mirror. Then two mirrors will reflect the laser ray twice onto the projection wall. Now we use the Webcam to monitor the laser projection. For home healthcare our design sends images captured by the Webcam to the embedded board which through digital image processing determines whether the breath rate is normal. The LCD displays the real-time status of the breath rate on the embedded board. If no signs of breath are detected, a warning message is sent to the hospital by the network. We use an embedded board instead of a PC because of its low power consumption and portability. In addition the embedded board reduces the cost, and one can use this system easily at home. It is thus convenient for home health application.
III. USING THE METHODS

A. DIFFERENCING METHOD

The temporal differencing method which reads the continuous image from the Webcam, then fetches the separated image and processes it at the gray level. This method finds the subtraction of the continuous images, chooses the threshold value for the decision, uses a Gaussian filter to remove noise and then obtains the moving object.

B. MAGNIFICATION METHOD

When a patient breathes, the chest displacement is small. So we propose the laser reflection method to enlarge the displacement of the chest to detect the breath rate more easily[4]. Fig.2 shows the projection length of the moving object. X is the downward displacement of the chest which can be amplified by laser reflection onto a tilted wall. Y is the projection length of the first reflection. The magnification of the first reflection is shown in Eqn. (1).

\[
\frac{Y}{X} = 2 \times (\sin \gamma \tan(\theta + \gamma) + \cos \gamma) \tag{1}
\]

Eqn.(1) shows the relationship between magnification and oblique angle of the wall which can provide a 10-times amplification if \(\theta \leq 75^\circ\) and \(\theta + \gamma \geq 80^\circ\). When \(\theta + \gamma \geq 80^\circ\), the projecting point on the wall will be so far away that the laser ray will generate some distortion. The total magnification of the laser reflection is shown in Eqn. (2).

\[
\frac{Z}{X} = 2 \times (\sin \gamma \tan(\theta + \gamma) + \cos \gamma)(\sin \rho \tan(\theta + \gamma + \rho) + \cos \rho) \tag{2}
\]

By using Eqn.(1) and Eqn. (2) we learn that the total magnification is the multiplication of the first and second reflection’s amplification. To avoid distortion of the laser projection we arrange the first reflection to be enlarged by about 4.5 times when \((\theta + \gamma) \geq 70^\circ\). Then we arrange \(\delta \geq 10^\circ\) so that the second reflection can be enlarged more than 2.2 times. Therefore we reach our goal of the laser projection being enlarged by more than 10 times with less distortion. Fig 2 indicates Projection length of the chest displacement.

IV. BREATH MONITORING

The subtraction of two continuous images results in different values when read in a different order of images. It is stored in the matrix, and the elements are reset to zero if this subtraction is negative, because the size of the 8-bit gray scale element is 0-255. The human body’s complete breath consists of the chest rising and falling, from maximum to minimum. If the chest rises to the maximum and then not only falls but also instantaneously changes direction, this development may cause a turning point. Three turning points are a complete breath cycle, and from them we calculate the breath rate. Three turning points are a complete breath cycle, and from them we calculate the breath rate. In addition we use our digital method to enlarge the body movement to increase the detection distance. Fig 3 is the Flowchart of breath rate detection and it also
determines the breath abnormalities. When the system detects no breath for more than 10 seconds, the system sends out a warning message. The judging method decides whether the patient’s condition is normal or not by detecting the breath rate.

![Flowchart for determining breath abnormalities.](image)

**V. IMPLEMENTATION RESULTS**

The implementation of the circuit, as it contains mainly four part power supply, microcontroller, switching circuit and transmission circuit. The basic block diagram of the circuit is shown below in Fig 4.

![Block Diagram](image)

**A. CALCULATION**

After processing our program provides four data which show “Direction”, “Transition”, “Number of Breaths” and “Breath Rate”. “Direction” shows the direction of the thoracic movement which synchronizes with the chest moving targets in the area underneath the camera, “Transition” is the calculation of the cumulative transition, “Number of Breaths” calculates the accumulation of the breathing, and “Breath Rate” shows the immediate breath rate. The relationship is shown in eqns.

**B. CASES**

Figs. 5, 6 & 7 show the three cases of breath displacement on the projection wall which demonstrates the chest expansion and contraction when the body breathes. The horizontal axis of the diagram is the time in seconds, and the vertical axis is the distance in centimetres on the projection wall. Denoted the transition when the directions of the two adjacent points in time are opposite each other. The Cases are given below about the breath displacement.

**C. CASE 1**

Fig.5 is the breath displacement of Case 1, which shows a recording time of 60 seconds with 16 full breaths. A normal man's respiratory rate is about 16 to 20 per minute, a woman’s about 18 to 22 and a newborn’s about 40 to 44. Thus a respiratory rate of 16 full breaths per minute is normal.
D. CASE 2

Fig.6 shows the breath displacement diagram of Case 2, which has the same recording time of 60 seconds with about 12 full breaths. Here the respiratory rate is 11.6 full breaths per minute. Obviously the respiratory rate is one full breath less than in Case 1. This result indicates that although the observed respiration is slower, it still does not harm the body.

E. CASE 3

Fig.7 shows the breath displacement diagram of Case 3, which has the same recording time of 60 seconds with 8 full breaths. But as there are two breathing stops of over 5 seconds, the respiratory rate is 8 full breaths per minute. This result indicates not only slow breathing, but also that the amplitude of the chest movement is less, and that there is a cessation of breathing of over 5 seconds. The breathing of this individual, therefore, is already in a bad state.

VI. FUTURE ENHANCEMENT

Fig.8: Block Diagram for future enhancement.
VII. CONCLUSION

Our design uses the low-power laser reflection method to spot the variation in the breath and Webcam is used to capture the image, the temporal differencing method for breath detection and an embedded board to monitor the patient’s breath without the inconvenience to the body because of any physical contact by the instrument. This design detects chest expansion and contraction more easily. The additional cost is small for monitoring a patient’s breath in home healthcare.

REFERENCES


